

# On the Natural Degree of Parallelism in Transactional Memory: from Centralized to Distributed Architectures

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- 2 The case of (non distributed) TM
- 3 The case of Distributed TM
- 4 Conclusions and Current Research

# Addressed Problem

Finding the maximum level of parallelism for a TM application, i.e., the number of threads

- below which adding threads improves throughput
- over which adding threads decreases throughput
  - ▶ even if sufficiently many cores are available

# Challenges

## Maximum Level of Parallelism is

- Workload specific
  - ▶ Data contention level
  - ▶ Transaction length
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- Platform dependent
  - ▶ Concurrency Control algorithm
  - ▶ Scale of the TM (i.e., centralized or distributed)

# Challenges

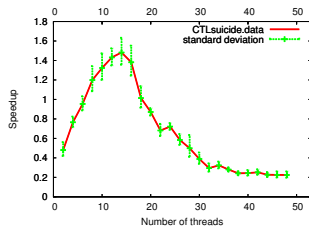
## Maximum Level of Parallelism is

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  - ▶ Transaction length
  - ▶ Read/Write operations ratio
- Platform dependent
  - ▶ Concurrency Control algorithm
  - ▶ Scale of the TM (i.e., centralized or distributed)
- ...and varies over time
  - ▶ Any static value is sub-optimal
  - ▶ Offline trial-and-error is non viable

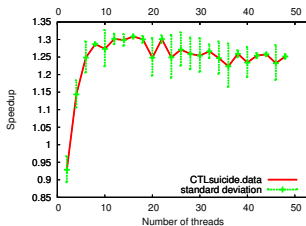
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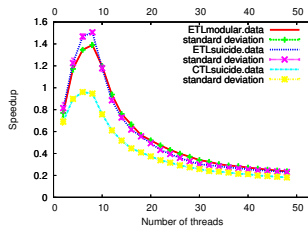
# Natural/Optimal Degree of Parallelism



## Kmeans-high



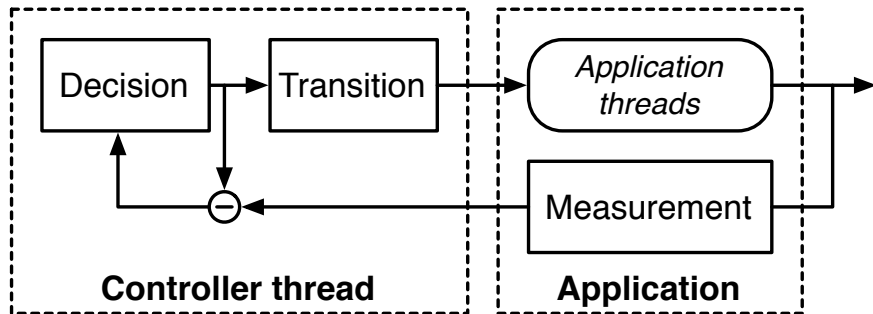
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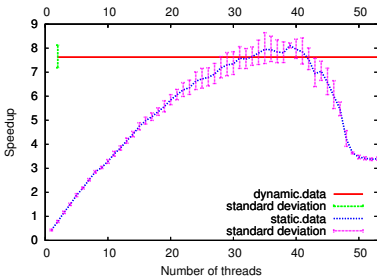
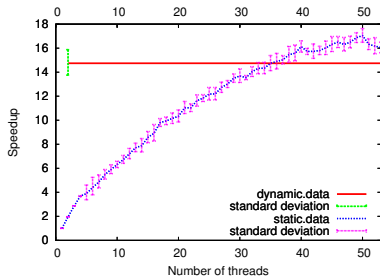


Intruder

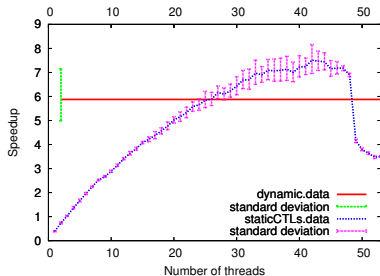


# Dynamic Thread Management

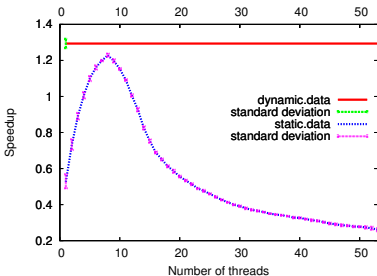




## Labyrinth



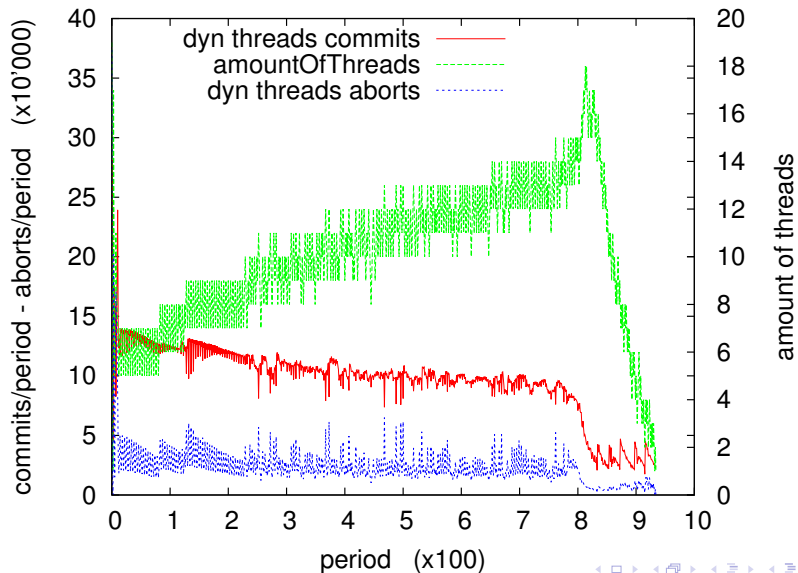
## Vacation-low



## Vacation-high

## Intruder

## During an Intruder Execution



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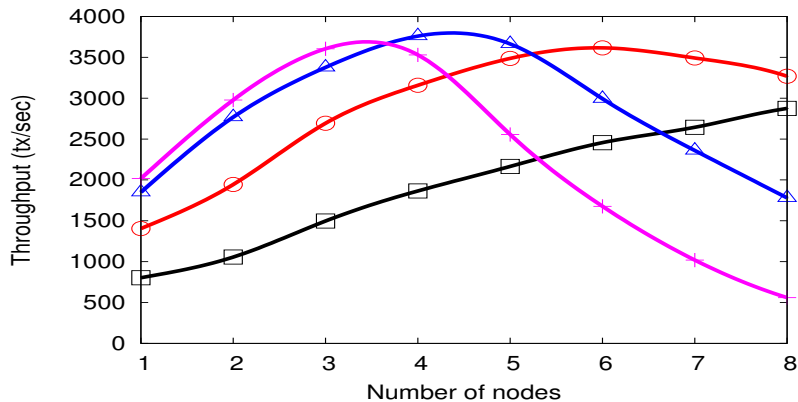
# Challenges

- Increase in the dimensionality of the problem
  - ▶ At single node level
    - # threads per node
    - Local execution time
  - ▶ At system level
    - #nodes in the DTM
    - Dominant distributed synchronization costs

# Case study: TPC-C Benchmark

## Infinispan as DTM

- Exclusive write lock taken locally at encounter time
- Two-phase commit for global consistency



2 th



4 th



6 th



8 th



# Maximum level of parallelism in DTM

- Efficiency of exploration-based techniques depends on the efficiency of exploration steps
  - ▶ Adding/removing threads in a centralized TM is cheap
  - ▶ Adding/remove nodes on a DTM is costly
    - involves state transfers
    - in Cloud, new replica = \$
    - introduces instability
    - requires global reconfiguration protocol

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Pure exploration-based techniques are cumbersome and inefficient in DTM

- What about predictive models?



# Model-based techniques

Predictive models allow to forecast the impact of adding/removing nodes on a DTM

- Target configuration reached in a single step
- Avoid useless state transfers

# Transactional Auto Scaler

System that given the current workload allows to predict the optimal scale for the DTM

- Joint usage of Analytical Models and Machine Learning
  - ▶ Analytical model captures logical contention (e.g., abort prob.)
  - ▶ Machine learning predicts physical layer's behavior (e.g., Rtt)
- General and modular methodology
  - ▶ We tailored it for Infinispan

# TAS' models

## Analytical Model

- White-box approach: knowledge of DTM consistency alg.
- Good extrapolation power
- Queueing theory

## Machine Learning

- Black-box approach: physical layer is hard to model
- Suitable for Virtualized environments
- Offline trained decision-tree regressors

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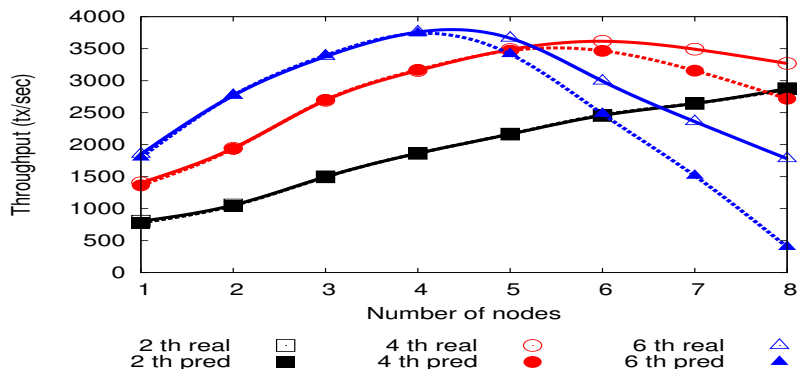


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## TAS accuracy

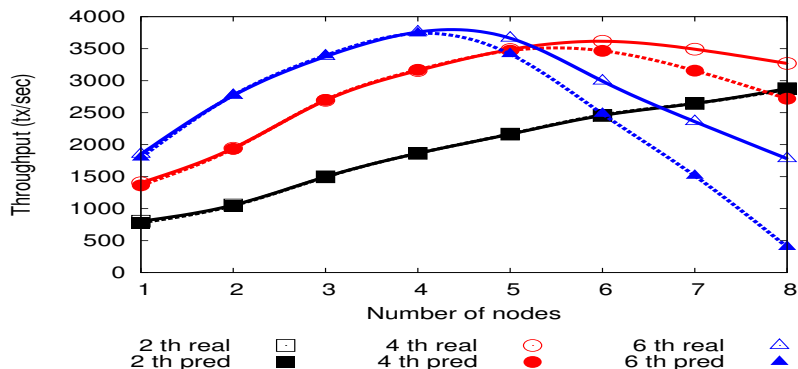
System performance predicted from scenario 2 nodes, 2 threads



- Very good accuracy in “similar” scenarios (e.g., same # threads)
- Ability to determine the optimal level of parallelism

## TAS accuracy

System performance predicted from scenario 2 nodes, 2 threads



- Loss of accuracy for configurations where
  - ▶ model's hypotheses are challenged (i.e., abort probability  $> 80\%$ )
  - ▶ machine learner has not been extensively trained

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# Towards a combined approach

- Exploration-based techniques are robust but not scalable to distributed settings
- Model-based techniques are more attractive for DTMs but can suffer from inaccuracy
- The two techniques can be jointly exploited
  - ▶ On-line exploration can improve model's accuracy
  - ▶ Analytical model can improve scalability of on-line technique



# Current research

Taking the best of the two worlds:

- Using predictive models to guide on-line exploration
  - ▶ goal: maximize convergence speed of on-line exploration
  
- Incorporating in the model the knowledge acquired with on-line exploration
  - ▶ goal: progressively enhance predictive model's accuracy

# Questions?

